



Control Flow Analysis for Recursion Removal

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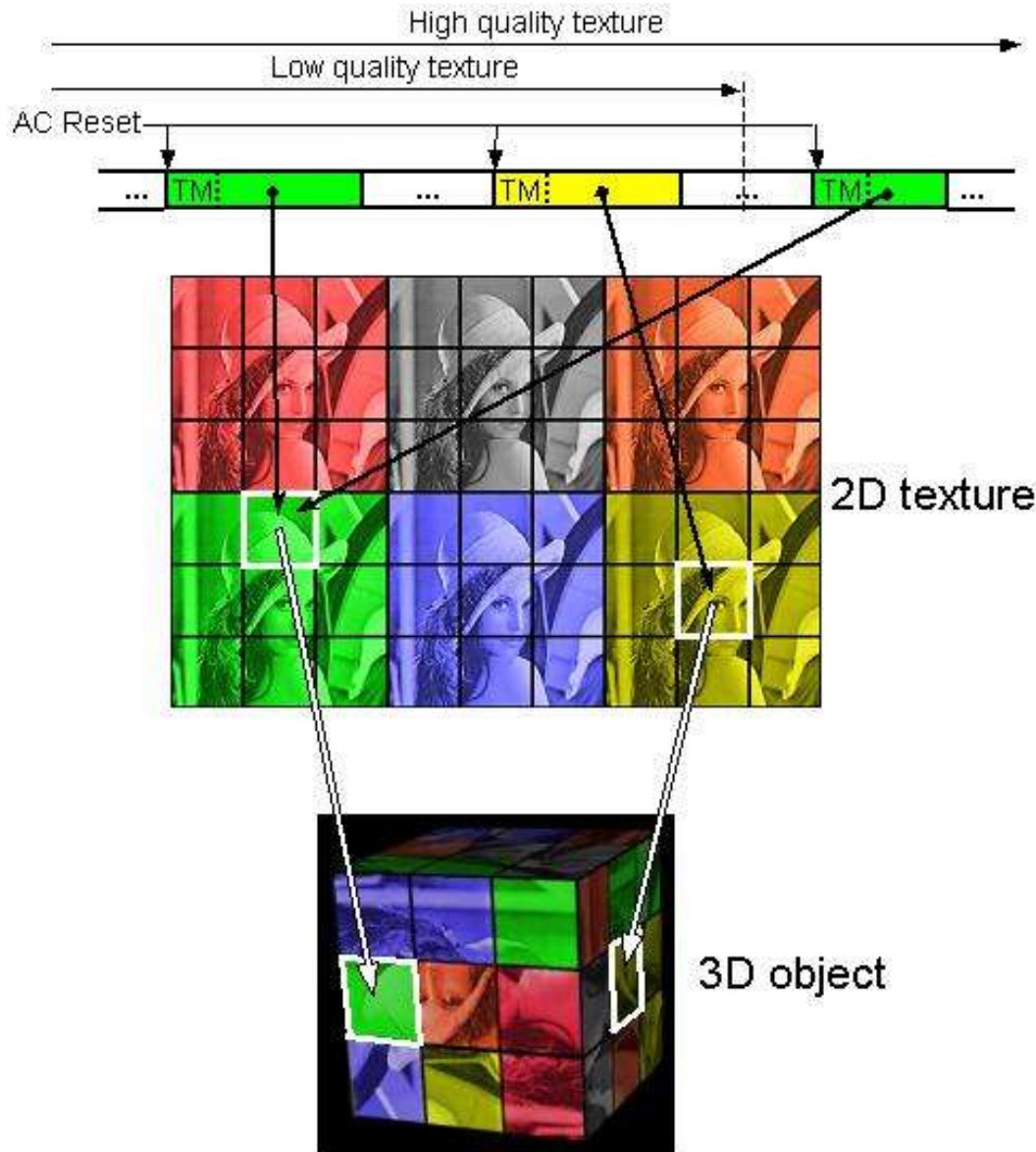
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Introduction

- Recursion removal
 - **Traditionally** done to reduce resource consumption (time and memory)
 - **Now** meant as **enabling step** for other transformations, typically on imperative or OO code (C/C++/JAVA/...)
 - Usually dependency removal transformations, and parallelising transformations
 - Hence, main goals:
 - Try to introduce as little new dependencies in iterative resulting algorithm implementation as possible
 - Guarantee correctness in presence of side-effects
 - However, it is still useful to evaluate impact on execution time, memory usage

Visual texture coding

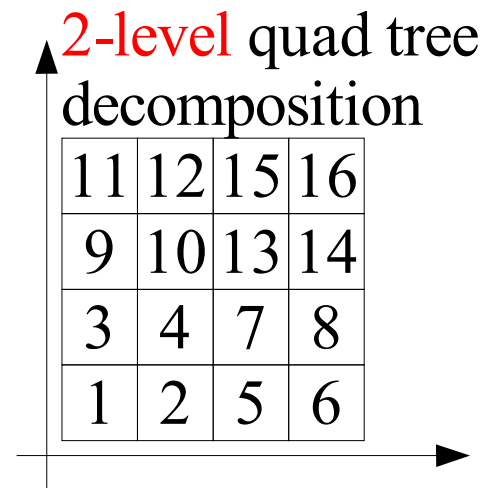
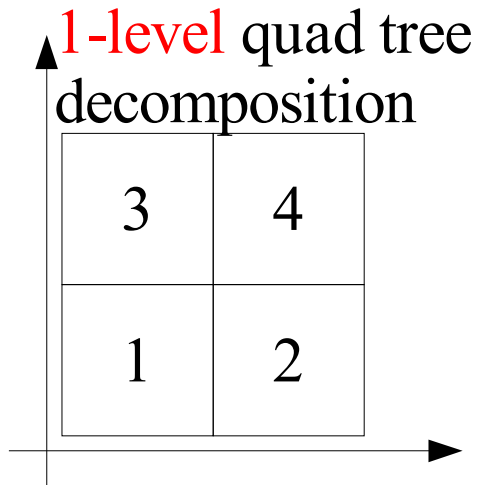


- Part of the MPEG-4 standard
- Transmission of still images
- Scalable
 - Quality: successive quantisation
 - Resolution: Wavelet based
 - Region of Interest (ROI) selection

AC = Arithmetic Coder
TM = Texture marker

Recursive part of the VTC algorithm

- MPEG 4 VTC



VTC algorithm (partial)

```

Decode (d, x, y) {
  if (d == 0) {
    DecodePixel(x,y);
  } else {
    --d; k=1<<d;
    Decode(d,x,y);
    if (d == 4) Check();
    Decode(d,x+k,y);
    if (d == 4) Check();
    Decode(d,x,y+k);
    if (d == 4) Check();
    Decode(d,x+k,y+k);
    if (d == 4) Check();
  }
}

```

Recursive part of the VTC algorithm

- Time spent in this part of VTC is 50% of overall time
- **DecodePixel** is expensive compared to argument trafo and recursive function calls
- Between recursive calls extra functionality is present
 - It has side-effects
 - It must be preserved

```
VTC algorithm (partial)
Decode (d, x, y) {
  if (d == 0) {
    DecodePixel(x,y);
  } else {
    --d; k=1<<d;
    Decode(d,x,y);
    if (d == 4) Check();
    Decode(d,x+k,y);
    if (d == 4) Check();
    Decode(d,x,y+k);
    if (d == 4) Check();
    Decode(d,x+k,y+k);
    if (d == 4) Check();
  }
}
```

Recursive part of the VTC algorithm

- **First step:**
 - **DecodePixel** is expensive
 - **DecodePixel** is activated with argument values that are transformed through recursion
- Hence
- First **collect argument values, store in memory**
 - Then use in iteration with **DecodePixel** calls

```
VTC algorithm (partial)
Decode (d, x, y) {
    if (d == 0) {
        DecodePixel(x,y);
    } else {
        --d; k=1<<d;
        Decode(d,x,y);
        if (d == 4) Check();
        Decode(d,x+k,y);
        if (d == 4) Check();
        Decode(d,x,y+k);
        if (d == 4) Check();
        Decode(d,x+k,y+k);
        if (d == 4) Check();
    }
}
```

Recursive part of the VTC algorithm

- **Second step:**
 - Storing collected values in memory is expensive
- Hence
- **Replace recursive information collection with a formula producing these same argument values**

```
VTC algorithm (partial)
Decode (d, x, y) {
  if (d == 0) {
    DecodePixel(x,y);
  } else {
    --d; k=1<<d;
    Decode(d,x,y);
    if (d == 4) Check();
    Decode(d,x+k,y);
    if (d == 4) Check();
    Decode(d,x,y+k);
    if (d == 4) Check();
    Decode(d,x+k,y+k);
    if (d == 4) Check();
  }
}
```

Step 1: separate base case calculation from recursion

- **Record** all information that is needed in base case, in the original recursive algorithm without base case calculation
 - Applied to VTC:
 - Leave out call to DecodePixel
 - Add recording of d, x, y values in algorithm
- **Loop** over all collected information
 - Each time calling DecodePixel with correct argument values retrieved from memory
 - This loop is fully parallelizable, if the side-effects inside DecodePixel do not interfere

Pseudo-code result

VTC algorithm (info collection)

```

Decode (d, x, y) {
  if (d == 0) {
    info[++cnt]=(x,y);
  } else {
    --d; k=1<<d;
    Decode(d,x,y);
    if (d==4) deq4[cnt]=1;
    Decode(d,x+k,y);
    if (d==4) deq4[cnt]=1;
    Decode(d,x,y+k);
    if (d==4) deq4[cnt]=1;
    Decode(d,x+k,y+k);
    if (d==4) deq4[cnt]=1;
  }
}

```

VTC algorithm (iterative part)

```

ItDecode(d,x,y) {
  Decode(d,0,0);
  for (i=0;i<cnt;i++) {
    DecodePixel(info[i]);
    if (deq4[i])
      Check();
  }
}

```

What has happened up to now?

- Recursive part of algorithm
 - Collects information
 - **No longer dominates execution time**
- Iterative part of algorithm
 - Uses collected information
 - **Method itself does not impose inter-iteration dependencies**
 - Hence: opportunity for parallelization
- Drawback
 - Storing all information needs a lot of memory, certainly a lot more than was needed in the recursion; bad for energy consumption

Step 2: replace recursive info collection with iterative info generation

- **Determine iteration bound**
 - Call to `Decode(d,_,_)` results in 4 calls to `Decode(d-1,_,_)`
 - Number of iterations easily found by solving recurrence equation

$$I(d) = 4 I(d - 1) \text{ with } I(0) = 1$$

- With solution

$$I(d) = 4^d$$

Step 2: replace recursive info collection with iterative info generation

- **Modeling of argument transformations**

- Call to Decode(d,x,y) results in 4 calls:

- Decode(d-1, x , y);

- Decode(d-1, x+k, y);

- Decode(d-1, x , y+k);

- Decode(d-1, x+k, y+k);

(with $k = 2^{(d-1)}$)

- Before base case is reached, arguments have undergone a large amount of additions with different k-values = **argument transformations**

Call tree

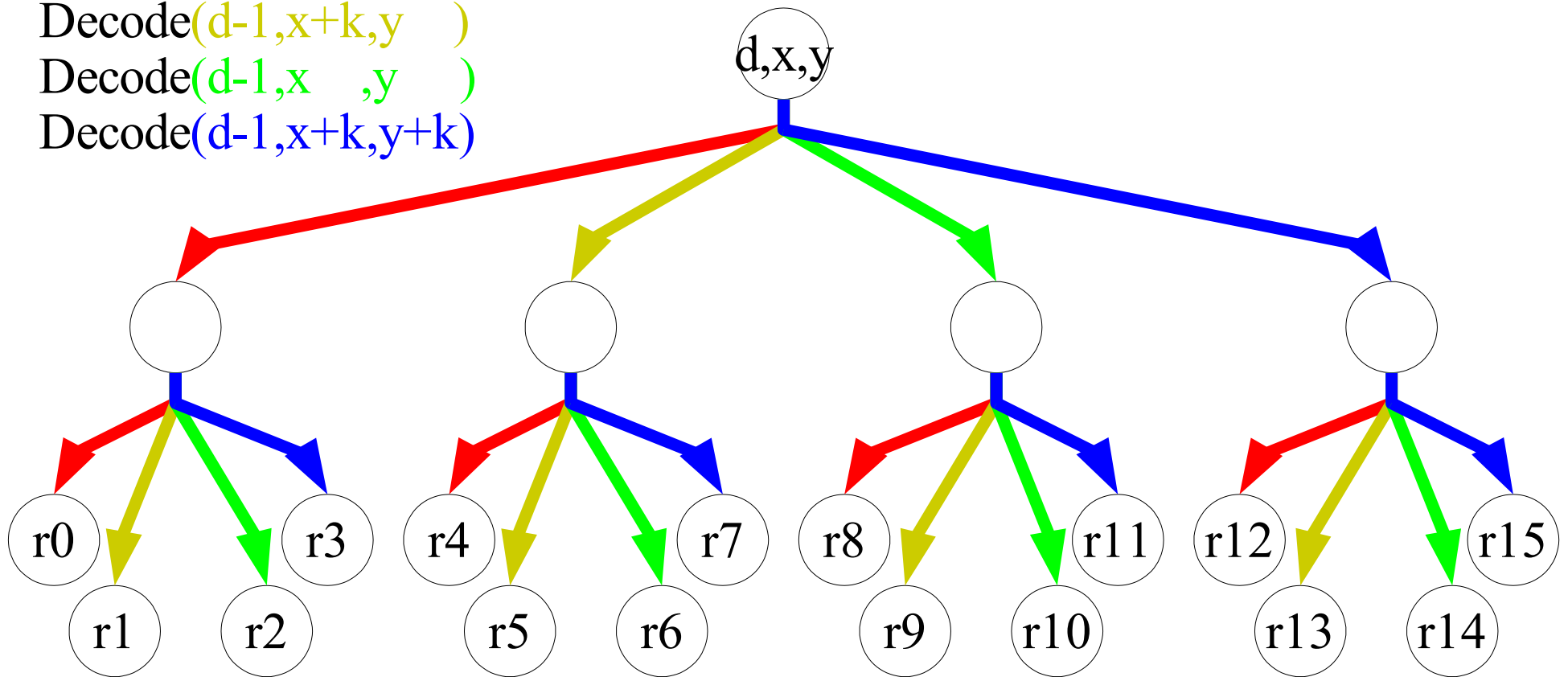
Example: call to $\text{Decode}(2,x,y)$ results in 4 calls:

$\text{Decode}(d-1,x,y)$

$\text{Decode}(d-1,x+k,y)$

$\text{Decode}(d-1,x,y+k)$

$\text{Decode}(d-1,x+k,y+k)$



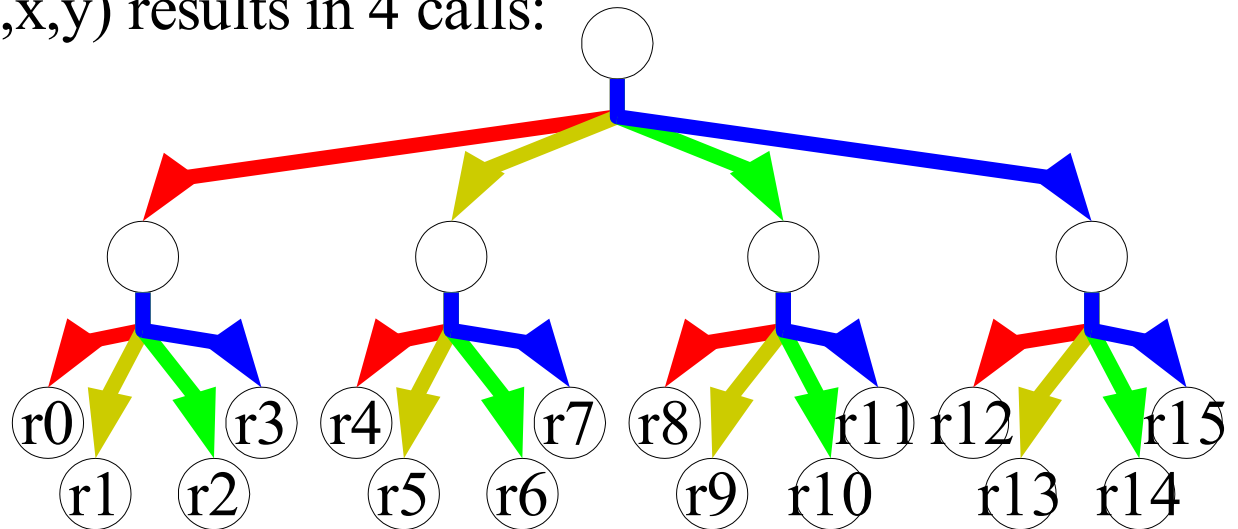
Problem:

How is (d,x,y) transformed through the recursion when reaching the base case?

Call tree

Example: call to Decode(2,x,y) results in 4 calls:

Decode(d-1,x ,y)
 Decode(d-1,x+k,y)
 Decode(d-1,x ,y)
 Decode(d-1,x+k,y+k)



Answer:

(for mathematical derivation: see paper)

$$r_j = \begin{matrix} 0 \\ \sum_{i=0}^{n-1} 2^i \left(\left(j \operatorname{div} 2^{2^i} \right) \bmod 2 \right) \\ \sum_{i=0}^{n-1} 2^i \left(\left(j \operatorname{div} 2^{2^{i+1}} \right) \bmod 2 \right) \end{matrix}$$

What has happened up to now?

VTC algorithm (info collection)

```
Decode (d, x, y) {  
  if (d==0) {  
    info[++cnt]=(x,y);  
  } else {  
    --d; k=1<<d;  
    Decode(d,x,y);  
    if (d==4) deq4[cnt]=1;  
    Decode(d,x+k,y);  
    if (d==4) deq4[cnt]=1;  
    Decode(d,x,y+k);  
    if (d==4) deq4[cnt]=1;  
    Decode(d,x+k,y+k);  
    if (d==4) deq4[cnt]=1;  
  }  
}
```

- Formula for r_j can be used to replace non-grayed out part of VTC with iteration
 - Synthesize a loop that calculates r_j values for $j = 0 .. 4^d$
- We have ignored the extra functionality between the recursive **Decode** calls
- Let's put it back in !

Handling intermediate functionality

- **Problem:** when must activation of

“if (d==4) Check()”

be scheduled, to preserve correctness in presence of side-effects inside Check() function ?

- **Strategy:**
 - We look for a relation $R(j)$ between iteration counter j (which calculates successive r_j 's) and the result of condition ($d == 4$)
 - Then iterative algorithm calculates r_j , followed by checking condition $R(j)$ and possible activation of intermediate functionality

Handling intermediate functionality

- Consider call to Decode(4,_,_)
 - This results in 4 calls to Decode(3,_,_)
 - Each of these 4 calls results in 4 calls to Decode (2,_,_) => $4*4 = 16$ calls
 - ...
 - Results in $4*4*4*4 = 256$ calls to Decode(0,_,_) (call to Decode(0,_,_) is what activates base case calculation!)
- **Conclusion:**
 - Between two calls to Decode(4,_,_) there are $4^4 = 256$ calls to Decode(d,_,_) with $d < 4$
 - Hence $(d == 4)$ is true if j is multiple of 256 !
 - Similarly $(d > 4)$ is true if j is multiple of 1024

Handling intermediate functionality

- Hence the following relation has been found

$$d = 4$$

\Leftrightarrow

$$j \bmod 256 = 0 \wedge j \bmod 1024 \neq 0$$

- Because 256 and 1024 are powers of two, this is cheaply implemented by bit masking

Resulting iterative VTC core

- **Iterative version**

```
for j = 0 to  $4^n - 1$  {  
    // calculate argument values
```

$$x_bc = \sum_{i=0}^{n-1} 2^i ((j \operatorname{div} 2^{2^i}) \bmod 2);$$

$$y_bc = \sum_{i=0}^{n-1} 2^i ((j \operatorname{div} 2^{2^{i+1}}) \bmod 2);$$

```
    // activate base case calculation  
    DecodePixel(x_bc,y_bc);
```

```
    // activation intermediate functionality
```

```
    if ((j mod 256 = 0) && (j mod 1024 ≠ 0))
```

```
        Check();
```

```
    }
```

Intermediate conclusions

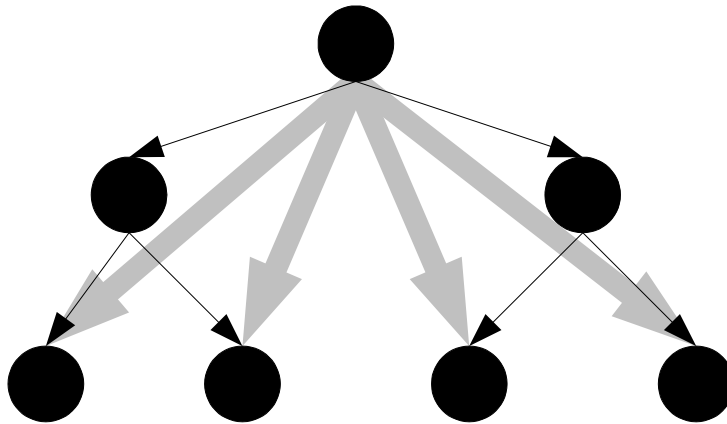
- What have we done up to now?
 - **Separate** base case calculation from recursion
 - To isolate dominant part from recursion
 - **Replace** argument recording with argument calculation
 - To remove argument recording memory usage
 - Solution to three sub-problems was required
 - Determination of iteration bound
 - Modeling argument transformations through the recursion
 - Activation of intermediate functionality at correct moments in time

Intermediate conclusions

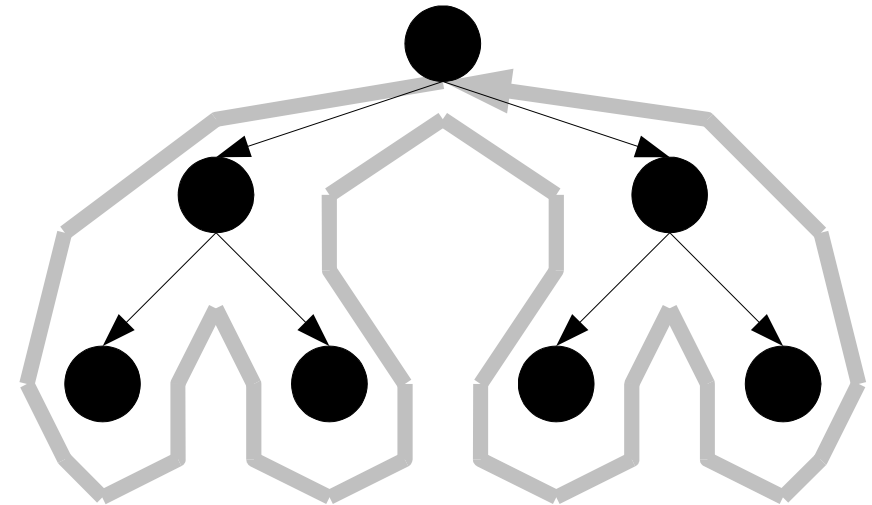
- How general is this approach ?
 - Has been **generalised** and **extended** to handle recursive algorithms with any combination of
 - Multiple base cases
 - Multiple recursive cases
 - Intermediate functionality which depends on any combination of recursive function arguments (or other arguments, e.g. global variables)
 - Any kind of argument transformation functions
 - Functions with return values and functions to combine return values to new return values
 - In the most general case **all functions may have side-effects**
 - So, **it is quite general!**

Comparison iterative - recursive

- **Iterative algorithm**



- **Recursive algorithm**

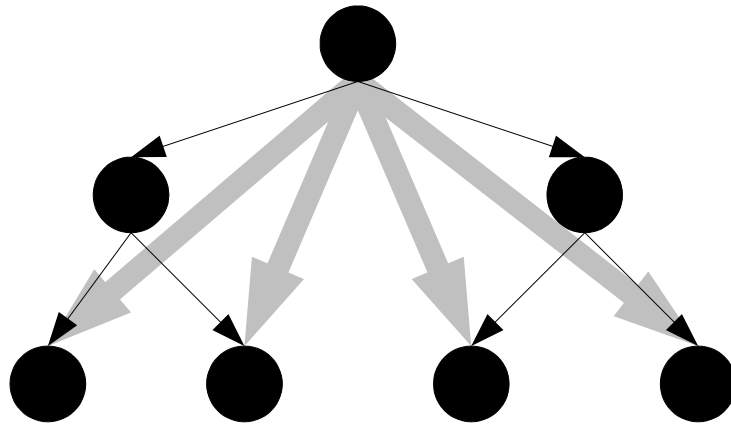


- Traverses each path from root node to leaf
- Arrows closer to root are evaluated more often than arrows nearer to leaf

- Performs depth-first traversal of call tree
- Each arrow is evaluated exactly once

Comparison calculation requirements

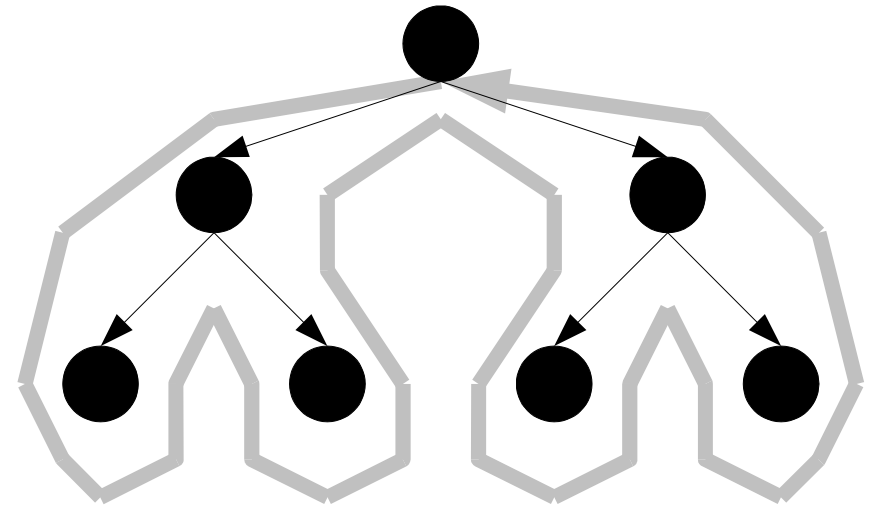
- Iterative algorithm**



- Each arrow represents
 - Function call
 - Argument trafo step

- There are (at most) $\frac{B^{D_{MAX}+1} - 1}{B - 1} - 1$ arrows

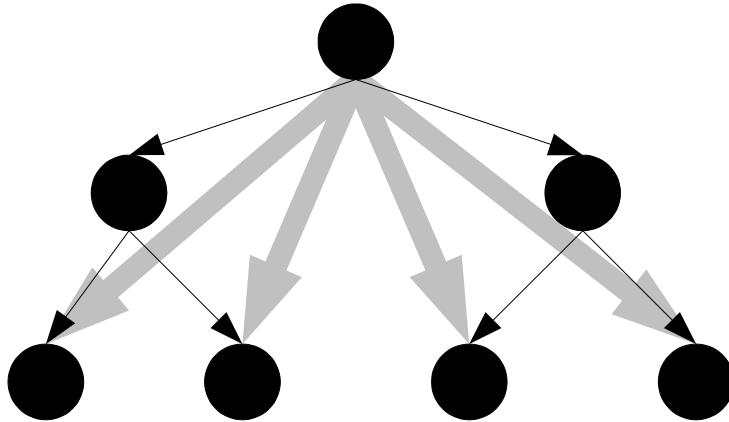
- Recursive algorithm**



- Each arrow represents
 - Argument trafo step
- Arrow from depth d to depth $d+1$ is redone (at most) $B^{D_{MAX}-1}$ times
- From depth d to $d+1$ there are B^{d+1} arrows
- Total #calcs = $D_{MAX} B^{D_{MAX}}$

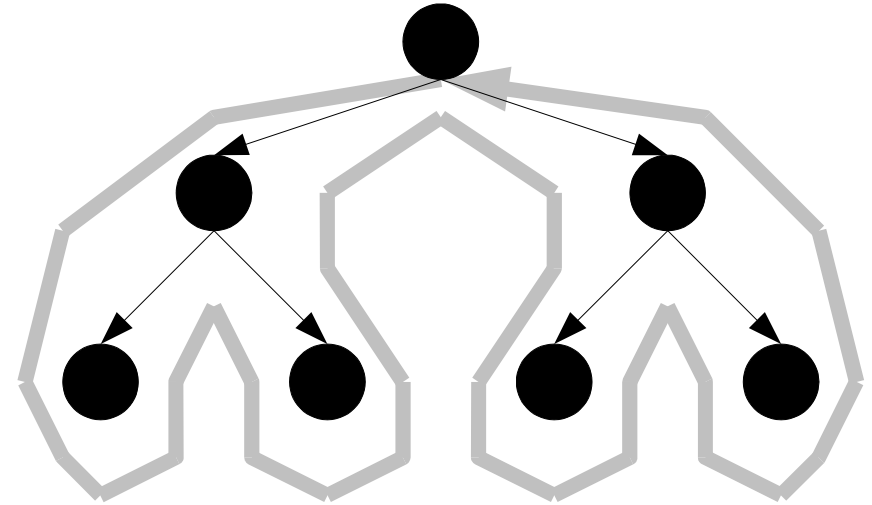
Comparison memory requirements

- **Iterative algorithm**



- Some fixed amount of book keeping memory required
- No extra memory depending on recursion depth

- **Recursive algorithm**



- Memory required is at most
= stack frame size X recursion depth

Systematic trade-offs

- **First trade-off:**
 - Trade-off **argument transformation calculations** versus **memory** used
 - By applying partial memoization
- **Second trade-off**
 - Trade-off **memoization memory** for **parallelizability**
 - By applying in-place optimization

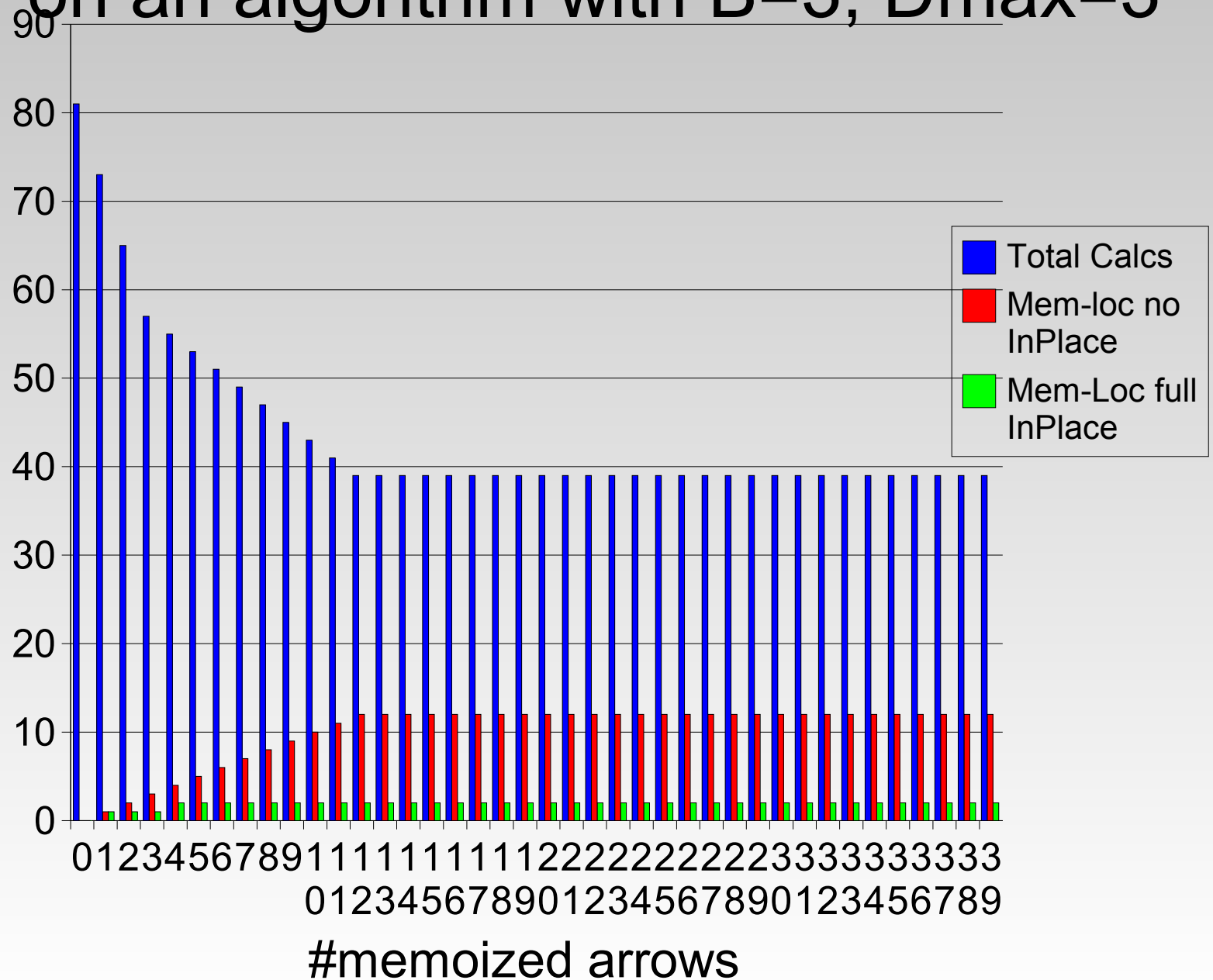
First trade-off: **calculations vs. memory**

- Storing results from argument transformation step going from depth d to $d+1$ reduces number of argument transformation steps with an amount of $B^{D_{MAX}-d} - 1$
- **Memoization of leaf does not have advantage** (leaf is needed only once, $B^{D_{MAX}-D_{MAX}} - 1 = 0$)
- Storing each result in separate memory location
 - Reduces amount of calculations to amount in recursive algorithm
 - But uses up to $\frac{B^{D_{MAX}+1} - 1}{B - 1} - 1$ memory locations
 - Recursive version needs only D_{max} locations
- This version **has potentially full parallelisability, but this is usually not needed**

Effect of memoization on #calcs, #mem



Effect of memoization on #calcs, #mem on an algorithm with $B=3$, $D_{max}=3$



Second trade-off: memory vs. parallelisability

- Not all argument transformation results are needed at the same time (unless fully parallelised version is desired)
- Hence memory locations can be reused
- By full memoization and fully exploiting limited life-times
 - Can achieve same time and memory complexity as recursive algorithm or better
 - This depends on such factors as
 - Known lack of side-effects in certain parts of the algorithm
 - Possibilities for symbolically simplifying r_j - equation

Summary of trade-offs

	Recursive calls	Argument trafo calcs	Memory locations	Parallel. oportunities
Recursive version	$\frac{B^{D_{MAX}+1} - 1}{B - 1} - 1$	$\frac{B^{D_{MAX}+1} - 1}{B - 1} - 1$	$S \cdot D_{MAX}$	none
Iterative version	0	$D_{MAX} B^{D_{MAX}}$	0	full
Iterative + partial memoization	0	Between $D_{MAX} B^{D_{MAX}}$ and $\frac{B^{D_{MAX}+1} - 1}{B - 1} - 1$	Between 0 and $\frac{B^{D_{MAX}+1} - 1}{B - 1} - 1$	full
Iterative + memoization + in-place	0	Between $D_{MAX} B^{D_{MAX}}$ and $\frac{B^{D_{MAX}+1} - 1}{B - 1} - 1$	Full memo: between $\frac{B^{D_{MAX}+1} - 1}{B - 1} - 1$ and $S' \cdot D_{MAX}$	Between full and none

Summary and future work

- Method for **removing and analysing recursion** in quite general cases
 - Here applied on VTC algorithm
 - Many other examples have been transformed as well
- Recursion removal on VTC **enabled** further transformation to get energy reduction of up to factor 2 (without reduction of execution time). For details, see:

Zhe Ma, Chun Wong, Stefaan Himpe, Eric Delfosse, Francky Catthoor and Geert Deconinck, “[Task concurrency analysis and exploration of Visual Texture Coder on a Heterogeneous Platform](#)”, in: Proceedings of the 2003 IEEE workshop on signal processing systems (SIPS03)



The End...

...thank you!

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